

PHYS 5040
Algebra and Topology in Physics
Spring 2021

Lecture 11

February 18

1 What is the Lie group $SO(3)$? What is its algebra?

$$SO(3) = \{ M \in \mathbb{R}^{3 \times 3} ; \det(M) = 1, M^T M = 1 \}$$

$\hookrightarrow 3 \times 3$ matrix w/ real coeff

rotation group in 3 dimension

classical example: Lagrangian for (non-rel.) universe

$$L = \sum_i \frac{1}{2} m \dot{\vec{x}}_i^2 - \sum_{i < j} V_{ij}(|\vec{x}_i - \vec{x}_j|)$$

L invariant if
 $\vec{x}_i \mapsto M \vec{x}_i$

since length preserved

$$(M \vec{a} \cdot \vec{a}) = \vec{a}^T M^T M \vec{a} = \vec{a} \cdot \vec{a}$$

Lie algebra $so(3)$: generators

$$M = 1 + \delta\theta^a T^a$$

last time: T^a are antisymmetric

$$T^{xy} = T^z = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}; T^{zx} = T^y = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{pmatrix}; T^{yz} = T^x = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$[T^x, T^y] = T^z; [T^y, T^z] = T^x; [T^z, T^x] = T^y \rightarrow \text{angular momentum}$$

2 What is the Lie group $SU(2)$? What is its algebra?

$$SU(2) = \{ M \in \mathbb{C}^{2 \times 2} : \det(M) = 1, M^\dagger M = \mathbb{1} \} \text{ unknown generators}$$

What's the Lie algebra? $M = \mathbb{1} + \delta\theta^a T^a$

$$\det(M) = \det(\mathbb{1} + \delta\theta^a T^a) = 1 + \delta\theta^a \text{tr}(T^a) = 1 : \text{tr}(T^a) = 0$$

$$(\mathbb{1} + \delta\theta^a (T^a)^\dagger)(\mathbb{1} + \delta\theta^b T^b) \approx \mathbb{1} + \underbrace{T^a \delta\theta^a + (T^a)^\dagger \delta\theta^a}_{=0} = \mathbb{1}$$

3 traceless Hermitian 2×2 's ... Pauli: $= 0$: if $\delta\theta^a \neq 0$...

$$\sigma^x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \sigma^y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \sigma^z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \xrightarrow[\text{on } a]{\text{no sum}} T^a \delta\theta^a = -\overline{\delta\theta^a} (T^a)^\dagger \text{ real}$$

$(T^a)^\dagger = T^a$ and $\delta\theta^a = i\delta\phi^a$

Lie algebra:

$$[\sigma^x, \sigma^y] = 2i\sigma^z$$

$$[\sigma^y, \sigma^z] = 2i\sigma^x$$

$$[\sigma^z, \sigma^x] = 2i\sigma^y$$

up to factor of $2i$...

$$T^x = \frac{1}{2i}\sigma^x, \text{ etc...}$$

$$[T^x, T^y] = T^z \dots \text{ exactly same as } \mathfrak{so}(3)$$

3 Review the "simultaneous diagonalization" of the angular momentum algebra.

angular momentum

$$[J_x, J_y] = i\hbar J_z \quad [J_z, J_x] = i\hbar J_y \quad [J_y, J_z] = i\hbar J_x$$

QM "solution" of this problem; ↑ be diagonal

$$J^2 = J_x^2 + J_y^2 + J_z^2 \dots \quad [J^2, J_x] = 0 = [J^2, J_y] = [J^2, J_z]$$

diag. simultaneously

$$J_{\pm} = J_x \pm iJ_y$$

$$[J_z, J_{\pm}] = \pm J_{\pm}$$

if $J_z|\psi\rangle = \mu|\psi\rangle$
then...

$$J_z(J_{\pm}|\psi\rangle) = (\mu \pm 1)J_{\pm}|\psi\rangle$$

either $\mu \pm 1$ is e-val
or $J_{\pm}|\psi\rangle = 0$.

$$J^2 = J_- J_+ + J_z^2 + J_z$$

$$\langle \psi | J^2 | \psi \rangle \geq 0$$

Combine...

max & min value of μ : $\pm \mu_*$

$$J^2|\psi\rangle = \mu_*(\mu_* + 1)|\psi\rangle \dots$$

all μ 's must differ by integer...

$$\mu_* \rightarrow j = 0, \frac{1}{2}, 1, \frac{3}{2}, \dots$$

4 What is the representation theory of $SU(2)$?

Started w/ $\mathfrak{su}(2)$ Lie algebra;

$$[J^2, J_z] = 0 : \quad J^2 |jm\rangle = j(j+1) |jm\rangle ; \quad \underline{J_z |jm\rangle = m |jm\rangle}$$
$$j = 0, \frac{1}{2}, 1, \dots \quad m = -j, -j+1, \dots, j$$

Suppose we have irrep R of $SU(2)$.

$\forall g \in SU(2), \exists R(g)$ obeys $R(g_1)R(g_2) = R(g_1g_2)$ AND R 's can't be sim. diag.

$$g_1 = 1 + i\delta\theta_1^a T^a \quad g_2 = 1 + i\delta\theta_2^a T^a$$

$$\begin{aligned} \rightarrow R(g_2^{-1})R(g_1)R(g_2) &= (1 - i\delta\theta_2^a T^a)(1 + i\delta\theta_1^a T^a)(1 + i\delta\theta_2^a T^a) \\ &= 1 + i\delta\theta_1^a R(T^a) - \delta\theta_1^a \delta\theta_2^b [R(T^a), R(T^b)] \\ &= R(g_2^{-1}g_1g_2) = R(1 + i\delta\theta_1^a T^a - \delta\theta_1^a \delta\theta_2^b [T^a, T^b]) \end{aligned}$$

$$\Rightarrow [R(T^a), R(T^b)] = R([T^a, T^b]) = f^{abc} R(T^c)$$

in any mom. algebra; $J_{\pm} |jm\rangle \propto |j(m\pm 1)\rangle$: space of fixed j

Can't simultaneously diag. $J_x, J_y, J_z \dots$ span $\{|j, -j\rangle, \dots, |j, j\rangle\}$

Claim: $j = 0, \frac{1}{2}, 1, \frac{3}{2}, 2, \dots$ are all finite-dim irreps is an irrep of $SU(2)$

5 What is the relationship between SU(2) and SO(3)?

Lie algebras $\mathfrak{so}(3) = \mathfrak{su}(2)$
↑
re-scaling generators

does this mean groups are isomorphic?
~~SO(3) = SU(2)~~
no

Why? [deep...] Problem 5d on HW #1:

rotate around z-axis: SO(3): $e^{\theta^z T^z} = \begin{pmatrix} \cos\theta^z & -\sin\theta^z & 0 \\ \sin\theta^z & \cos\theta^z & 0 \\ 0 & 0 & 1 \end{pmatrix}$

SU(2): $e^{\theta^z T^z} = e^{-i\frac{1}{2}\sigma^z\theta^z} = \begin{pmatrix} e^{-i\theta^z/2} & 0 \\ 0 & e^{i\theta^z/2} \end{pmatrix}$ $j = \frac{1}{2}$

$\theta^z = 2\pi$: SO(3) \rightarrow 1 SU(2) \rightarrow -1

#1: $j=0, 1, 2, \dots$ are irreps of SO(3)

#2: spin $-\frac{1}{2}$ electron, etc... predicted by group theory

6 Discuss two common conventions for the irreps of $SU(2)$.

Choice #1: spin j

irreps: $0, \frac{1}{2}, 1, \frac{3}{2}, \dots$
1-dim \nearrow 2-dim \nearrow 3-dim \nearrow

Choice #2: (HEP) dimension

irreps: [**boldface**] $1, 2, 3, 4, \dots$
1-dim \nearrow 2-dim \nearrow

7 What is the representation theory interpretation of the "addition of angular momentum" problem in quantum mechanics?

Example: spin- $\frac{1}{2}$ electron in $l=2$ state of hydrogen;
what are possible values of total spin?

$$\begin{array}{ccc} 2 & \otimes & \frac{1}{2} \\ \uparrow & & \uparrow \\ l & & s \\ \text{tensor product} & & \text{direct sum} \\ \text{of irreps} & & \text{decomposes into irreps} \end{array} = \frac{3}{2} \oplus \frac{5}{2}$$

\uparrow
 j

$|n, l, m\rangle |s, m_s\rangle$

Rule: $j_1 \otimes j_2 = |j_1 - j_2| \oplus (|j_1 - j_2| + 1) \oplus \dots \oplus (j_1 + j_2)$

HEP notation: $5 \otimes 2 = 4 \oplus 6$

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What is the representation theory interpretation of the hydrogen atom's selection rules?

H atom [any isotropic system]
energy states

$|n l m\rangle$
energy level \uparrow
group/rep indices

$$\mathbb{SO}(3) = \mathbb{SO}(3) \times \mathbb{Z}_2$$

$$\vec{r} = -\vec{r}$$

l irrep $l=0,1,2,\dots$
 $m = -l, -l+1, \dots, l$

Selection rules:

Why is the $l=l'$ transition forbidden?

$\mathbb{O}(3)$ irreps:

$0_+, 1_-, 2_+, 3_-, 4_+, \dots$

E.g. $l=2 \rightarrow l=1 \dots$

$$1_- \subset 1_- \otimes 2_+ \\ = 1_- \oplus 2_- \oplus 3_-$$

$|n l m\rangle$ $\xrightarrow{\text{spont. emission}}$ $|n' l' m'\rangle$

$$l' = l \pm 1$$

$$m' = m \pm 1 \text{ or } m$$

$$\langle n l m | \vec{p} | n' l' m' \rangle \neq 0$$

$\uparrow \quad \uparrow \quad \uparrow$
 $j=1$

need $l < 1 \otimes l'$
 $= (l'-1) \oplus l' \oplus (l'+1)$