

PHYS 5210
Graduate Classical Mechanics
Fall 2022

Lecture 14

Noether's Theorem for fields

September 23

1 Extend Lagrangian field theory to higher dimensions.

$$S = \int dt dx \mathcal{L}(\phi, \partial_t \phi, \partial_x \phi) \quad (\partial_t \phi = \frac{\partial \phi}{\partial t})$$

Principle of least action:

$$0 = \frac{\delta S}{\delta \phi(x,t)} = \frac{\partial \mathcal{L}}{\partial \phi} - \partial_t \frac{\partial \mathcal{L}}{\partial (\partial_t \phi)} - \partial_x \frac{\partial \mathcal{L}}{\partial (\partial_x \phi)}$$

In higher dimensions: $x^\mu = (t, x, y, z, \dots)$ $\frac{\partial \phi}{\partial x^\mu} = \partial_\mu \phi$

$$\rightarrow S = \int d^D x \mathcal{L}(\phi_a, \partial_\mu \phi_a, \dots)$$

a = different kinds of fields

μ = spacetime index

$$\sum_\mu \frac{\partial}{\partial x^\mu} \frac{\partial \mathcal{L}}{\partial (\partial_\mu \phi_a)} = \frac{\partial}{\partial t} \dots + \frac{\partial}{\partial x} \dots + \dots$$

Euler-L:

$$0 = \frac{\delta S}{\delta \phi_a(x)} = \frac{\partial \mathcal{L}}{\partial \phi_a} - \underbrace{\partial_\mu \frac{\partial \mathcal{L}}{\partial (\partial_\mu \phi_a)}}_{\text{Euler-L}}$$

2 State Noether's Theorem for fields.

Suppose S is invariant:

$$\phi_a \rightarrow \phi_a + \epsilon g_a; \quad x^M \rightarrow x^M + \epsilon Y^M; \quad \mathcal{L} \rightarrow \mathcal{L} + \epsilon \overbrace{\partial_\mu K^M}^{\text{total divergence}}$$

Noether's Thm: $\partial_\mu J^M = 0$ on physical trajectories, where
(state w/o proof)

$$J^M = \mathcal{L} Y^M - \frac{\partial \mathcal{L}}{\partial(\partial_\nu \phi_a)} \partial_\nu \phi_a Y^\nu + \frac{\partial \mathcal{L}}{\partial(\partial_\mu \phi_a)} g_a + K^M$$

Before: conserved Q ($\frac{dQ}{dt} = 0$ on phys./ext. traj)

$$\partial_\mu J^M = \frac{\partial J^t}{\partial t} + \frac{\partial J^x}{\partial x} = 0$$

- conservation
+

- spacetime locality

Conserved quantity?

$$Q = \int dx J^t?$$

$$\begin{aligned} \frac{dQ}{dt} &= \int dx \partial_t J^t = - \int dx \partial_x J^x \\ &= -J_x(\infty) + J_x(-\infty) = 0. \end{aligned}$$

3 What is the physical origin of $X(x, t) \rightarrow X(x, t) + \epsilon$ symmetry in a solid? What is the consequence?

Recall: 1d solid, block started at x moves to $X(x, t)$

$$\mathcal{L} = \frac{\rho}{2} \left[(\partial_t X)^2 - v_s^2 (\partial_x X)^2 \right]$$

Notice: \mathcal{L} invariant if $X \rightarrow X + \epsilon$ [$g=1$]

Why? global displacement cost no energy
(universe agnostic to $X=0$).

Noether's Thm: $J^\mu = (J^t, J^x)$

$$J^t = \frac{\partial \mathcal{L}}{\partial (\partial_t X)} = \rho \partial_t X$$

momentum
density (?)

$$J^x = \frac{\partial \mathcal{L}}{\partial (\partial_x X)} = -\rho v_s^2 \partial_x X$$

↙ E-L eqn.

$$\partial_\mu J^\mu = 0 = \partial_t J^t + \partial_x J^x = \rho \left[\partial_t^2 X - v_s^2 \partial_x^2 X \right]$$

4 What is the consequence of time-translation symmetry?

Symmetry: $t \rightarrow t + \epsilon$ $[Y^t = 1, Y^x = 0]$

$$\left[\rho = \frac{m_{\text{micro}}}{a_{\text{micro}}} \right]$$

$$J_{(TT)}^t = \mathcal{L} - \frac{\partial \mathcal{L}}{\partial (\partial_t X)} \partial_t X = -\frac{\rho v_s^2}{2} (\partial_x X)^2 - \frac{\rho}{2} (\partial_t X)^2$$

= - [energy dens.] = - pot. - kin. energy

$$J_{(TT)}^x = -\frac{\partial \mathcal{L}}{\partial (\partial_x X)} \partial_t X = \rho v_s^2 \partial_x X \partial_t X$$

t-comp \rightarrow \downarrow

\hookrightarrow t, x components of stress-energy (energy-mom.) tensor.

$$-J_{(TT)}^t \rightarrow T^{tt}$$

$$-J_{(TT)}^x \rightarrow T^{xt}$$

$$\partial_t T^{tt} + \partial_x T^{xt} = 0? = \rho \partial_t X \left[\partial_t^2 X - v_s^2 \partial_x^2 X \right]$$

$$\partial_t T^{tt} = \rho \left[\partial_t X \partial_t^2 X + v_s^2 \partial_x X \partial_x \partial_t X \right] = 0! \quad \text{"on shell"}$$

$$\partial_x T^{xt} = -\rho v_s^2 \left[\partial_x^2 X \partial_t X + \partial_x X \partial_x \partial_t X \right]$$

5 What is the consequence of space-translation symmetry?

Also: $x \rightarrow x + \epsilon$ $[Y^t = 0, Y^x = 1]$

$$J_{(ST)}^t = - \frac{\partial \mathcal{L}}{\partial (\partial_t X)} \partial_x X = - \rho \partial_t X \partial_x X = - T^{tx}$$

$$J_{(ST)}^x = \mathcal{L} - \frac{\partial \mathcal{L}}{\partial (\partial_x X)} \partial_x X = \frac{\rho}{2} (\partial_t X)^2 + \frac{\rho}{2} v_s^2 (\partial_x X)^2 = - T^{xx}$$

Again: $\partial_\mu J_{(ST)}^\mu = 0$

$$T^{tx} = \rho \partial_t X \partial_x X \rightarrow \approx \text{in/near equil.}$$

Recall: in equil.

$$X = x$$

↑ actual loc. of displaced
 ↑ pos. of block at rest

$$T^{xx} = - \frac{\rho}{2} [(\partial_t X)^2 + v_s^2 (\partial_x X)^2] \quad \text{infinitesimal}$$

Linearized dynamics: $X = x + \delta X$:

$$T^{tx} = \rho [\partial_t \delta X + \cancel{\partial_t \delta X \cdot \partial_x \delta X}] ; \quad T^{xx} \approx -\rho v_s^2 \partial_x \delta X$$