

PHYS 5210
Graduate Classical Mechanics
Fall 2022

Lecture 25

Symplectic manifolds and canonical transformations

October 19

1 Define a symplectic manifold (heuristically).

Lagrangian: 1) find Config. Space: M , n -dim manifold if n DOFs. (eg. \mathbb{R}^n , $SO(3)$...)

2) $S = \int dt L$, extremize S .

Hamiltonian:

(M, ω) is symplectic manifold

1) find phase space: manifold M
 M is $2n$ -dim if n DOFs
local coords: (q_i, p_i) $\rightarrow \left[\begin{array}{c|c} & \text{nxn} \\ \hline 0 & -1 \\ \hline 1 & 0 \end{array} \right]$

2) Find symplectic form: $\omega_{IJ} = -\omega_{JI}$

- closed: $\partial_I \omega_{JK} + \partial_J \omega_{KI} + \partial_K \omega_{IJ} = 0$.
- non-degenerate: ω^{-1} exists. (ω^{IJ})

3) Pick "any" function $H: M \rightarrow \mathbb{R}$ (Hamiltonian).

$\rightarrow \dot{f} = [f, H] + \frac{\partial f}{\partial t}$

where $[f, H] = \omega^{IJ} \partial_I f \partial_J H$.

2 Define a canonical transformation.

Symplectic manifold.

Goal: find coord. transforms. that leave (M, ω) invariant.

Such a coord. transform is called canonical (CT)

How does ω transform? To figure out, $\frac{\partial f}{\partial \xi} = 0$, and

$$\dot{f} = [f, H] = \omega^{IJ} \partial_I f \partial_J H = \omega^{IJ} \left(\frac{\partial f}{\partial \xi^I} \frac{\partial H}{\partial \xi^J} \right)$$

If transform $\xi^I \rightarrow \xi^I(\eta)$ [assume invertible]

Need: $\dot{f} = \omega^{IJ} \left(\frac{\partial f}{\partial \eta^I} \frac{\partial H}{\partial \eta^J} \right)$ use chain rule:

$$= \omega^{IJ} \left(\frac{\partial \xi^K}{\partial \eta^I} \frac{\partial f}{\partial \xi^K} \right) \left(\frac{\partial \xi^L}{\partial \eta^J} \frac{\partial H}{\partial \xi^L} \right) = \underbrace{\left(\frac{\partial \xi^K}{\partial \eta^I} \omega^{IJ} \frac{\partial \xi^L}{\partial \eta^J} \right)}_{\text{need}} \frac{\partial f}{\partial \xi^K} \frac{\partial H}{\partial \xi^L}$$

Invert:

$$\omega_{KL} = \frac{\partial \eta^I}{\partial \xi^K} \omega^{IJ} \frac{\partial \eta^J}{\partial \xi^L}$$

need

$$\omega^{KL} = \frac{\partial \xi^K}{\partial \eta^I} \omega^{IJ} \frac{\partial \xi^L}{\partial \eta^J}$$

3

Give an example of a canonical transformation for the harmonic oscillator.

harmonic oscillator: $H = \frac{p^2}{2} + \frac{q^2}{2}$ ($m=\omega=1$) (Step 3)

Steps 1 & 2: $M = \mathbb{R}^2$ & $\omega_{IT} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ $\begin{matrix} x \\ p \end{matrix}$

Ex. 1: $p' = p + 1$ or $x' = x + 1$.
These are CTs but H changes.

Ex. 2: $p' = \lambda p$ and $x' = \frac{1}{\lambda} x$
 $\omega_{p'x'} = \omega_{p'x'} = \frac{\partial p'}{\partial p} \omega_{p'x'} \frac{\partial x'}{\partial x} = \lambda \cdot 1 \cdot \frac{1}{\lambda} = 1$. ✓

Ex. 3: $\begin{pmatrix} p' \\ q' \end{pmatrix} = \begin{pmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} p \\ q \end{pmatrix}$.
• Since this is rot: $H = \frac{(p')^2 + (q')^2}{2}$.

• can check it's CT explicitly as above...
 $\omega_{p'x'} = \frac{\partial \mathcal{L}' / \partial p'}{\partial p} \omega_{IT} \frac{\partial \mathcal{L}' / \partial x'}{\partial x}$

4

Show that under time evolution, the mapping $\xi^I \rightarrow \xi^I(t)$ is a canonical transformation.
e.g. Ex. 3.

$$\xi^I(0) \xrightarrow[\text{CT}]{\text{goal:}} \xi^I(dt) \xrightarrow[\text{CT}]{} \xi^I(2dt) \xrightarrow[\text{CT}]{} \dots \xrightarrow[\text{CT}]{} \xi^I(t)$$

Use Hamilton's eq: $\dot{\xi}^I = [\xi^I, H]$

$$\xi^I(dt) \approx \xi^I(0) + dt \underbrace{[\xi^I, H]}_{\omega^{IJ} \partial_J H}$$

$$\frac{\partial \xi^I(dt)}{\partial \xi^J(0)} = \delta^I_J + dt \cdot \omega^{IK} \partial_J \partial_K H$$

Check CT: $w_{KL} = \frac{\partial \xi^I(dt)}{\partial \xi^K(0)} w_{IJ} \frac{\partial \xi^J(dt)}{\partial \xi^L(0)} = \delta^I_I$

$$\begin{aligned} \cancel{w}_{KL} &= \delta^I_K \cancel{w}_{IS} \delta^J_L + dt \left[\delta^I_K \underbrace{\omega_{IJ} \omega^{JM}}_{\omega^{IM}} \partial_M \partial_L H \right. \\ &\quad \left. + \omega^{IM} \partial_M \partial_K H \omega_{IJ} \delta^J_L \right] \\ &= -\delta^M_J \end{aligned}$$

$$+ dt [\partial_K \partial_L H - \partial_L \partial_K H] = 0.$$