

PHYS 5210
Graduate Classical Mechanics
Fall 2022

Lecture 26

Generating functions of canonical transformations

October 21

1 Review the definition of a canonical transformation.

Hamiltonian mech defined on symplectic manifold

(phase space) \mathbb{Z}_n -dimens. $\xrightarrow{(M, \omega)}$ $\xleftarrow{\omega_{IJ} = -\omega_{JI}}$ invertible

Canonical transformation = coord changes that leave ω unchanged.

Consider: $M = \mathbb{R}^2$, $w = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$

$$\begin{pmatrix} x' \\ p' \end{pmatrix} = \begin{pmatrix} x+1 \\ p \end{pmatrix}, \quad \begin{pmatrix} x' \\ p' \end{pmatrix} = \begin{pmatrix} 2 & 0 \\ 0 & y_2 \end{pmatrix} \begin{pmatrix} x \\ p \end{pmatrix}, \quad \begin{pmatrix} x' \\ p' \end{pmatrix} = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ p \end{pmatrix}$$

canonical canonical

$\mathfrak{I} \rightarrow \mathfrak{I}(\eta)$ is canonical if it's invertible, and

$$(2n) \quad w_{IJ}(\xi(\eta)) = \frac{\partial \xi^K}{\partial \eta^I} w_{KL}(\xi(\eta)) \frac{\partial \xi^L}{\partial \eta^J}$$

$$= [f, H]$$

true in both coords. \S & η .
[if transform. is t-independent]

2 Show that canonical transformations must come from a single generating function (up to topological obstructions...).

$$w_{IJ}(\xi) = \frac{\partial \alpha_J}{\partial \xi^I} - \frac{\partial \alpha_I}{\partial \xi^J} \quad \xrightarrow{\text{e.g. if}} \quad w = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}_p$$

$\alpha = \begin{pmatrix} p \\ q \end{pmatrix}; \quad \underline{\alpha = pdx}$

math fact from topology.

Suppose we have CT $(q_i, p_i) \rightarrow (Q_j, P_j)$, and

$$\alpha = p_i dq_i \quad \text{OR} \quad A = P_j dQ_j$$

$$\text{If: } w(p, q) - w(P, Q) = 0 \underset{(\text{if } \alpha)}{\equiv} \Delta w: \quad \Delta w_{IJ} = \frac{\partial \Delta \alpha_J}{\partial \xi^I} - \frac{\partial \Delta \alpha_I}{\partial \xi^J} = 0.$$

$$\text{Hence } \underline{\Delta \alpha_J = \partial_J F}. \quad \text{Write} \quad \Delta \overset{\downarrow}{\alpha} = \underline{dF = p_i dq_i - P_j dQ_j}.$$

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Discuss a type 1 canonical transformation.

Suppose $F(q_i, Q_i)$, $Q_i(q, p)$, H are all t -independent.

$$dF = p_i dq_i - P_i dQ_i : \left[p_i = \frac{\partial F}{\partial q_i} \text{ and } P_i = -\frac{\partial F}{\partial Q_i} \right]$$

Assume "invertible": one (q, Q) for each p_i or P_i .

Type I: (q, Q) are independent.

$$H(Q_i, P_i) = H(q(Q, P), p(Q, P))$$

Example: $M = \mathbb{R}^2$, $\omega = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$. $Q = \cos\theta q + \sin\theta p$, $P = \cos\theta p - \sin\theta q$

$$0 < \theta < \pi$$

$$p = \frac{Q - q \cos\theta}{\sin\theta} = \frac{\partial F}{\partial q}$$

$$= \csc\theta \cdot Q - q \cot\theta$$

$$F = -\frac{q^2}{2} \cot\theta + qQ \csc\theta - \frac{Q^2}{2} \cot\theta.$$

Similarly:

$$P = \cot\theta Q - \csc\theta \cdot q$$

If CT F has t -dep:

$$H_{\text{new}}(Q, P) = H_{\text{old}}(Q, P) + \frac{\partial F}{\partial t}$$

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What are type 2,3,4 canonical transformations?

Type 2 CT: (q, P) independent. Leg endne transform

$$F^2(q, P, t) = F_2(q, Q(q, P, t), t) + P_i Q_i$$

$$H_{\text{new}} = H_{\text{old}} + \frac{\partial F^2}{\partial t}$$

$$P_i = \frac{\partial F^2}{\partial q_i}, \quad Q_i = \frac{\partial F^2}{\partial P_i}$$

Type 3 CT: (p, Q)

$$F^3 = F - p_i q_i \quad [dF^3 = dF - p_i dq_i - q_i dp_i]$$

$$\text{etc...} \quad q_i = -\frac{\partial F^3}{\partial p_i}, \quad P_i = -\frac{\partial F^3}{\partial Q_i} \quad \text{etc...}$$

Type 4 CT: (p, P) $F^4 = F - p_i q_i + P_i Q_i$

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Discuss the one-parameter family of canonical transforms generated by a function f .