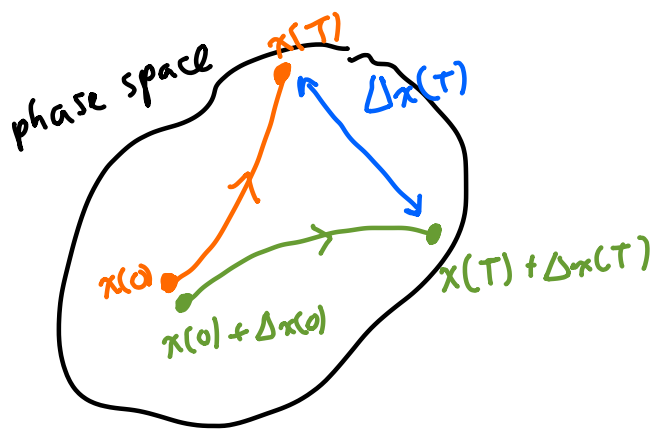


PHYS 5210
Graduate Classical Mechanics
Fall 2023

Lecture 41
The butterfly effect

December 8

Butterfly effect: exponential sensitivity of chaotic dynamics to initial conditions.



$\Delta x(T) \sim e^{\lambda T}$ ← Lyapunov exponent

Can write as:

$$\left| \frac{\partial x(T)}{\partial x(0)} \right| \sim e^{\lambda T}$$

Is butterfly effect good diagnostic for chaos?

▷ No! exponential sensitivity near saddle point in Hamiltonian mechanics:

(HW9) $H = xp \quad \{x, p\} = 1$

↳ $\dot{x} = \frac{\partial H}{\partial p} = x \quad \text{So} \quad x(T) = x(0)e^{\lambda T} \quad (\lambda = 1)$

But $p(T) = p(0) e^{-T}$ (Liouville Thm).

Still true that for "generic" $z = a\pi + bp$,

$$\left| \frac{\partial z(T)}{\partial z(0)} \right| \sim e^T \quad (T \rightarrow \infty)$$

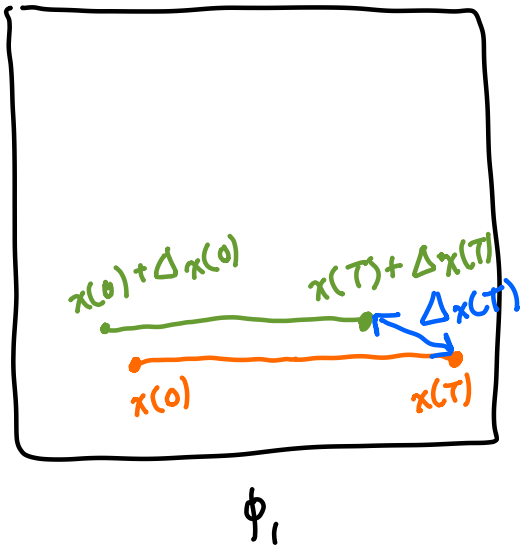
YES? (after addressing caveat above)

In Hamiltonian mechanics, integrability \rightarrow action-angle variables?

$\hookrightarrow H(J_A)$:

$$\dot{\phi}_A = \frac{\partial H}{\partial J_A} = \text{const.}$$

$$\dot{J}_A = -\frac{\partial H}{\partial \phi_A} = 0.$$



$$\begin{aligned} \Delta x(T) &\sim \sqrt{\Delta J_1(T)^2 + \Delta \phi_1(T)^2} \\ &\sim \sqrt{\Delta J_1^2 + (\Delta \phi_1(0) + T \cdot \Delta \omega_1)^2} \\ &\quad \begin{array}{l} \underbrace{\Delta J_1^2}_{\dot{J}=0} \\ \uparrow \\ = \frac{\partial H}{\partial J_1} \sim \Delta J \end{array} \\ &\sim T \cdot \Delta J \\ &\hookrightarrow \text{vs. } e^{\lambda T} \text{ for butterfly...} \end{aligned}$$

See no butterfly effect in an integrable system for generic initial conditions.

lec 42: chaos via proliferation of saddles?

Example: logistic map: $x_{n+1} = r x_n (1 - x_n)$

$$\begin{aligned} 0 \leq x_n \leq 1 \\ 0 \leq r \leq 4 \end{aligned}$$

Study trajectories:

$$x_0, x_1, x_2, \dots$$

$$x_0 + \delta x_0, x_1 + \delta x_1, x_2 + \delta x_2$$

choose $r=3.6$
so chaos

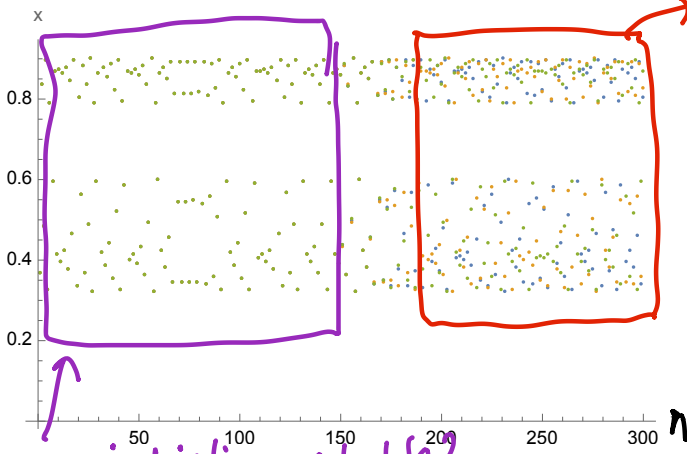
For generic ICs, $\delta x_n \rightarrow \mathcal{O}(1)$ as $n \rightarrow \infty$? How fast?

Numerical experiment! 3 runs w/ similar init. cond:

$$x_0 = 0.37$$

$$x_0 = 0.37 + 10^{-15}$$

$$x_0 = 0.37 - 10^{-15}$$



all 3 trajectories appear different
 ↓
 chaos!
 butterfly effect.

trajectories indistinguishable?

Estimate Lyapunov exponent?

$$\delta x_n \sim \delta x_0 \cdot e^{\lambda n}$$

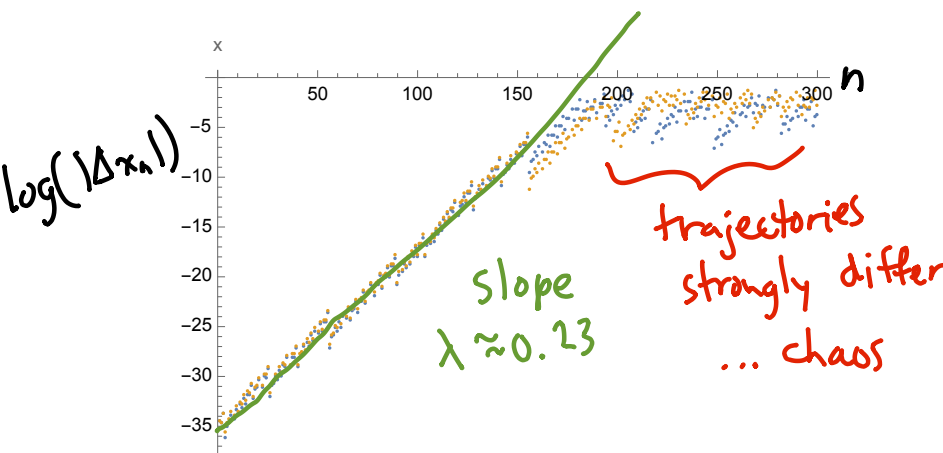
$$1 \cdot 10^{-15} \cdot e^{\lambda \cdot 150}$$

$$10^{15} \sim e^{150\lambda}$$

$$15 \log(10) \approx 150\lambda \rightarrow \lambda \approx 0.23$$

Note: λ independent of x_0 (more later)

Confirm exponential growth directly.



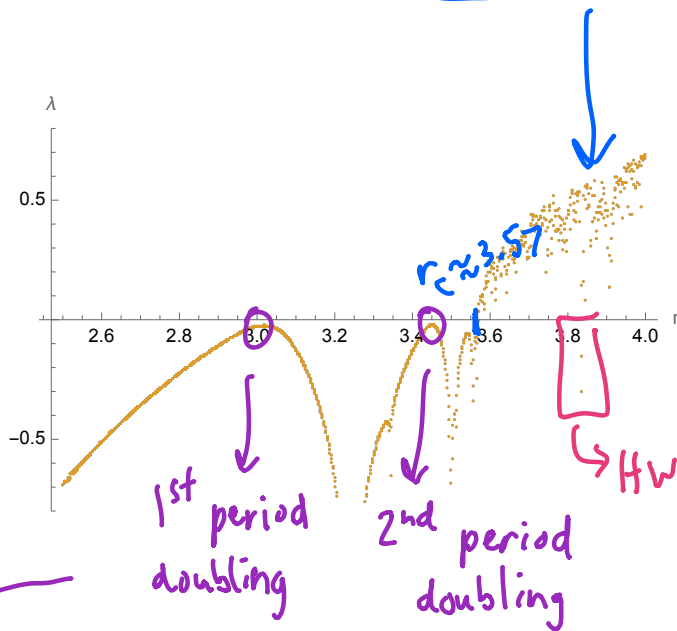
slope
 $\lambda \approx 0.23$

Exponential growth
 crucial to
 butterfly effect.

$$\Delta x_n \sim \Delta x_0 e^{\lambda n}$$

$$\log |\Delta x_n| \approx \log |\Delta x_0| + \lambda n$$

Claim: $\lambda > 0$ heralds chaos in logistic map



Calculated λ from $x_0^{(1)}$ & $x_0^{(2)}$.
(Measure slope of above line...)

Repeat at multiple r ...

$\hookrightarrow \lambda$ independent of x_0 .

\hookrightarrow HW13: stable period-3 cycle

Associated w/ $\lambda \rightarrow 0$ because e.g. approach $r \rightarrow 3^-$, one (from below!)

stable fixed pt becoming unstable. (lec 37) linear stability...

$$x_* + \delta x_n \sim \lambda_* (x_* + \delta x_{n-1})$$

\uparrow
fix pt

$\hookrightarrow |\lambda_*| \rightarrow 1$ as $r \rightarrow 3$.

$$\lambda_* \sim e^{-\lambda}$$

$\hookrightarrow \lambda \rightarrow 0$