

PHYS 5210
Graduate Classical Mechanics
Fall 2024

Lecture 29
Action-angle variables

November 1

Lec 27: Type 2 CT from $(x_i, p_i) \rightarrow (X_i, P_i)$
 assume that (x_i, P_i) are independent coords

$$dF_2 = p_i dx_i + X_i dP_i$$

gen func $\hookrightarrow p_i = \frac{\partial F_2}{\partial x_i}$ and $X_i = \frac{\partial F_2}{\partial P_i}$

Goal: clever CT to reveal integrability. (solvability)
 w/ t-ind. type 2 CT: $H = H(P_i)$

Then: $\dot{X}_i = \frac{\partial H}{\partial P_i}$ and $\dot{P}_i = -\frac{\partial H}{\partial X_i} = 0$

$X_i = \text{const.} = \omega_i$ So $P_i = \text{const.}$

$X_i(t) = X_i(0) + \omega_i(\hat{P})t$ $P_i(t) = P_i(0)$.

Assume: H is t-ind. and thus F_2 t-ind.

If we find such nice coords... call them action-angle variables

$$x_i \rightarrow \phi_A \quad (\text{angle})$$

ABC... denote A-A variables.

$$P_i \rightarrow J_A \quad (\text{action})$$

General, no sum convention on repeated indices

How to find J_A ?

Motivation: if $H = \dots$ solved by separation of variables:

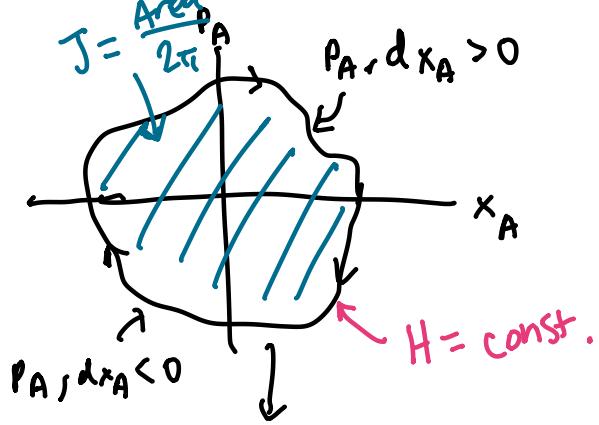
$$S(x_A, t) = -Et + \sum_A W_A(x_A; X) \quad \text{integration const.}$$

$$p_A = \frac{\partial W_A(x, X)}{\partial x_A} \quad \text{const. of motion } \Downarrow$$

Idea to extract X_A :

$$J_A = \frac{1}{2\pi} \oint p_A dx_A \quad \text{"action variables"}$$

$$J_A = \frac{1}{2\pi} \oint dx_A p_A = \frac{1}{2\pi} \oint dx_A \frac{\partial W_A}{\partial x_A} \stackrel{?}{=} \frac{1}{2\pi} \oint dW_A \cancel{= 0 ?} \quad \text{no!}$$



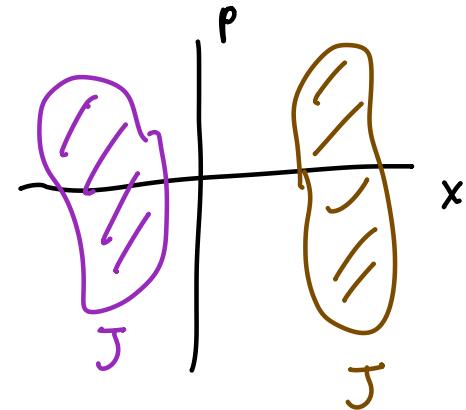
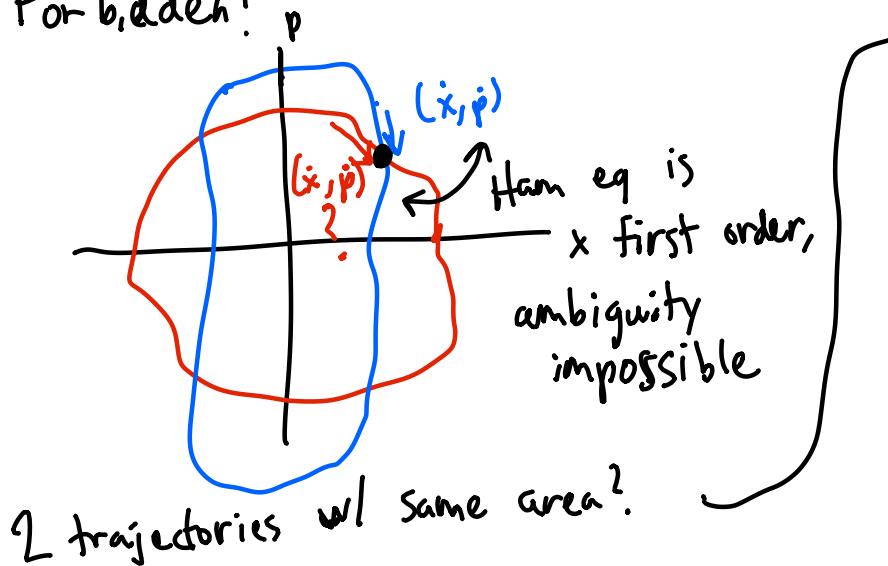
interpret integral as area enclosed in phase space

[Assumption here: trajectory is closed...
(can try to generalize...)]

trajectory associated to sol'n of Hamilton's eqs.

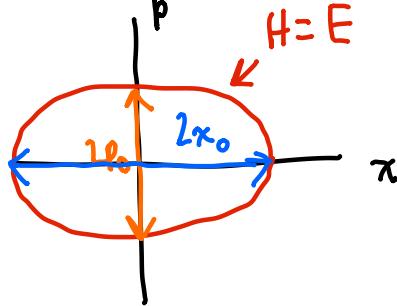
→ since stay on same traj for all t , J_A is a const. of motion

Forbidden!



This case allowed →
AA vars may not be global
(HW 10)

Example: harmonic oscillator $H = \frac{p^2}{2m} + \frac{1}{2}m\omega^2 x^2$



trajectory = curve w/ const. H .
ellipse

$$E = \frac{p_0^2}{2m} \quad \text{or} \quad p_0 = \sqrt{2mE}$$

$$E = \frac{1}{2}m\omega^2 x_0^2 \quad \text{or} \quad x_0 = \sqrt{\frac{2E}{m\omega^2}}$$

Action $J = \frac{\text{Area}}{2\pi} = \frac{\pi x_0 p_0}{2\pi} \rightarrow \frac{\pi \cdot x_0 \cdot p_0}{(\text{circle area})}$ rescale factor to get to unit circle

$$J = \frac{E}{\omega}$$

Therefore $H(J) = \omega J$

Hamilton's eqs:

$$\dot{J} = -\frac{\partial H}{\partial \phi} = 0 \quad \checkmark$$

$$J(t) = J(0)$$

$$\dot{\phi} = \frac{\partial H}{\partial J} = \omega$$

$$\phi(t) = \phi(0) + \omega t$$

$$p = p_0 \cos \phi$$

$$x = x_0 \sin \phi$$

$$p = \sqrt{2m\omega J} \cos \phi$$

$$x = \sqrt{\frac{2J}{m\omega}} \sin \phi$$

Check canonical:

$$\begin{aligned} \{x, p\} &= \sqrt{\frac{2}{m\omega}} \sqrt{2m\omega} \left\{ \sqrt{J} \sin \phi, \sqrt{J} \cos \phi \right\} \\ &= 2 \left[\frac{\partial(\sqrt{J} \sin \phi)}{\partial \phi} \frac{\partial(\sqrt{J} \cos \phi)}{\partial J} - \frac{\partial(\sqrt{J} \sin \phi)}{\partial J} \frac{\partial(\sqrt{J} \cos \phi)}{\partial \phi} \right] \\ &= \frac{\sqrt{J}}{\sqrt{J}} [\cos^2 \phi + \sin^2 \phi] = 1 \quad !! \end{aligned}$$

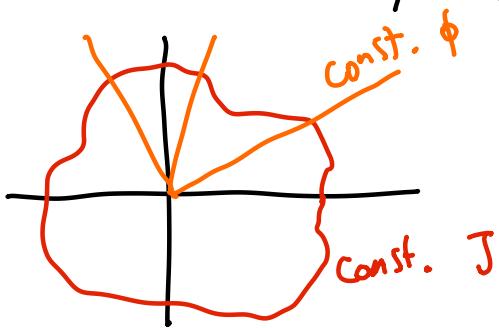
Usually, goal is just J .

Note $\phi \sim \phi + 2\pi$ is periodic.

Recap: action-angle variables are natural canonical conjugate coords for integrable systems...

$$H = H(J_A) \text{ so } \dot{J}_A = -\frac{\partial H}{\partial \phi_A} = 0 \quad \begin{matrix} \downarrow \\ \text{n const. of motion} \end{matrix} \quad \dot{\phi}_A = \frac{\partial H}{\partial J_A} = \text{const.} = \omega_A \quad \text{so } \phi_A(t) = \phi_A(0) + \omega_A t$$

AA is usually better than HJ?



- J have nice phase space interpretation
- when orbits closed, $\phi_A \sim \phi_A + 2\pi$

nice geometric picture of phase space (lec 31, ...)

Connection to QM: Bohr-Sommerfeld quantization

→ find AA variables...

Conjecture: $J_A = n_A \hbar \quad n_A = 1, 2, 3, \dots$

discrete energy levels: $E_{n_1, \dots, n_k} = H(n_1 \hbar, n_2 \hbar, \dots, n_k \hbar)$

in $2k$ -dim phase space

↳ "derive" via WKB approximation up to $n_A \rightarrow n_A - \frac{1}{2}$