

PHYS 7810  
Hydrodynamics  
Spring 2024

Lecture 27

Viscoelastic solids

April 25

To day: Solids are hydrodynamic w/ translation SSB



State is NOT invariant under translation symmetry.

For simplicity, neglect mass/energy conservation.

Noether's Thm: translation symmetry



momentum conservation

lec 25: account for SSB by adding Goldstone boson  
as a hydro DOF.

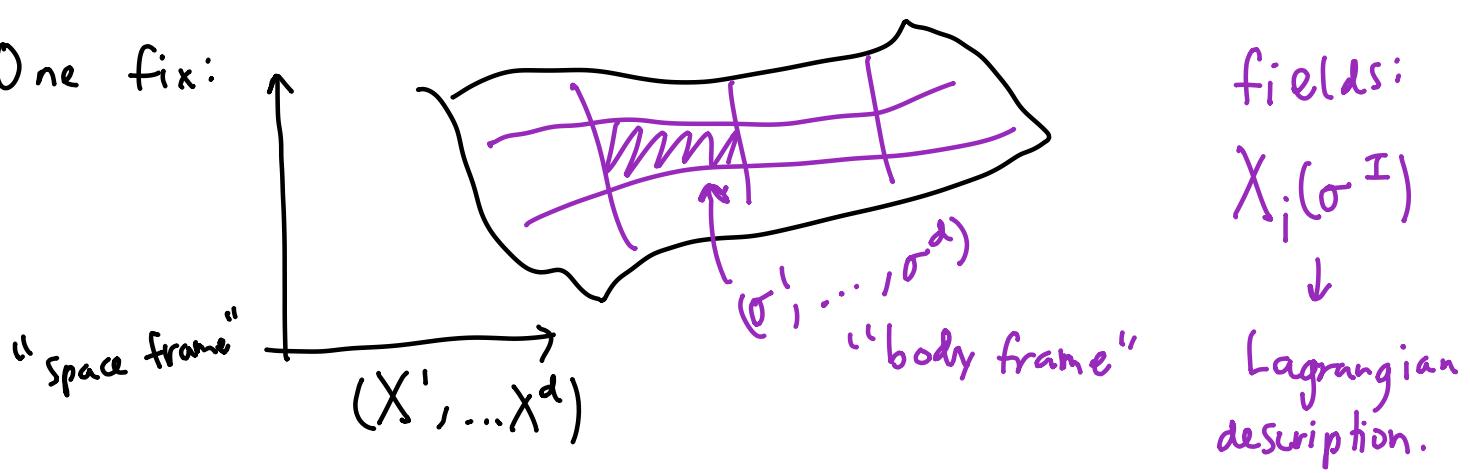
$X_i$  = position of solid

We have canonical Poisson bracket:

$$\{ X_i(x), g_j(x) \} = \delta_{ij} \delta(x - x')$$

Awkward b/c...  $X$  is also a coordinate?

One fix:



fields:

$$X_i(\sigma^I)$$

↓  
Lagrangian  
description.

Complication:

$$\frac{d}{dt} \int d^d X g_i(X) = 0 \quad \text{NOT} \quad \frac{d}{dt} \int d^d \sigma g_i(\sigma) = 0.$$

Alternative possibility: Eulerian description:  $\sigma^I(X_i)$

Technical: this requires  $\sigma(X)$  invertible.

Neglect since focus on long wavelength

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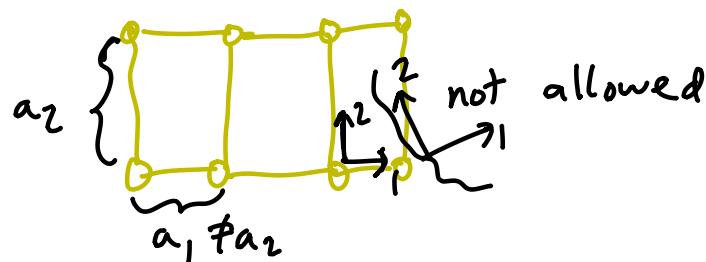
Before MSR: what are symmetries?

→ translation symmetry:  $X_i \rightarrow X_i + c$

→ space frame rotation:  $X_i \rightarrow R_{ij} X_j$

→  $\sigma^I \rightarrow \sigma^I + c$  ("relabeling")

→ NOT have  $\sigma^I$  rotation sym!



Important: anisotropic crystals ...  
... small crystals in 3d

Next: building  $\Phi$  (steady state)

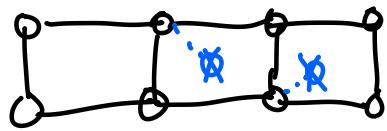
Crude:  $\Phi = \beta \int d^d X \underbrace{\frac{K_{ij}}{2} g_i g_j}_{\text{"}\sum p \gamma_{2m}\text{"}} + \dots \Phi_{el}[X]$

(analogy to lec 25)

translation:  $\Phi_{el}[X] = \Phi_{el}[X + c]$   
or  $\Phi_{el} = \int d^d X f(\underbrace{\partial^I X_i}_{\text{use Lagrangian desc.}}, \dots)$

What's  $\sigma$ ? Make a useful choice:

Solid have preferred equilibria:



$$\sigma^I = \delta_i^I X_i + \text{const.}$$

↳ labels each cell's position "at rest"

Notice:  $\partial^I X_i$  should be orthogonal:  $\partial^I X_i \cdot \partial^J X_i = \delta^{IJ}$ .

Now postulate: "elastic moduli"  
encode crystal's symmetry group

$$\Phi_{el} = \beta \int d^d X \frac{1}{8} \lambda^{IJKL} (\partial^I X_i \partial^J X_i - \delta^{II}) (\partial^K X_j \partial^L X_j - \delta^{KL})$$

↳  $d^d \sigma \det \left[ \frac{\partial X}{\partial \sigma} \right] \approx 1$

$\lambda^{(IJ)(KL)}$  should be positive semidefinite  $\rightarrow$  thermodynamic stability.

Note:  $K_{ij} \rightarrow \partial^I X_i \partial^J X_j \underbrace{K^{IJ}}_{\text{anisotropic?}}$

Focus on small perturbations near equilibrium

$$\tau^I = \delta_i^I (X_i + \phi_i(\sigma))$$

↳  $\approx \phi_i(X)$  to lowest order in  $\sigma$ .

Lazy: (in linear response / leading order in  $\phi$ ):

$$\{ \phi_i^{(0)}, g_j(x') \} = \delta_{ij} \delta(x - x')$$

Hydro EFT:  $\mathcal{L}_{MSR}(\phi_i, \pi_{\phi_i}, g_i, \pi_{g_i})$

$\downarrow$                      $\downarrow$   
 $\pi_i$                      $\psi_i$

Under time-reversal:  $g \rightarrow -g$        $\phi \rightarrow \phi$        $\mu_i = \frac{\delta \Phi}{\delta \phi_i}$   
 $\psi_i \rightarrow \psi_i - i \frac{\delta \Phi}{\delta g_i}$        $\pi \rightarrow -\pi + i \mu_\phi$   
 $\psi_i - i v_i$        $c = \beta v_i$

$$\mathcal{L}_{MSR} = \pi_i \partial_t \phi_i + \psi_i \partial_t g_i - T(\pi_i v_i - \psi_i \mu_i) + i \eta_{ijkl}^T \partial_i \psi_j \partial_k (\psi_l - i v_l)$$

dissipate (viscous)

momentum conservation:  $\psi_i \rightarrow \psi_i + c_i$

$$v_i = \frac{1}{T} v_i = \frac{1}{T} \eta_{ij} g_j$$

$$\mu_i = \frac{\delta \Phi_{el}}{\delta \phi_i} \dots \frac{\delta \Phi}{\delta x_i} \approx -\frac{\beta}{4} (\lambda^{IJKL} + \lambda^{JIKL}) \partial^I \partial^J x_i (\partial^K \partial^L x_j - \delta^{KL})$$

$$\approx -\frac{\beta}{4} (\lambda^{IJKL} + \lambda^{JIKL}) \partial^I \delta_i^J (\partial^K \phi^L + \partial^L \phi^K)$$

$$\rightarrow -\beta \lambda_{ijkl} \partial_j \partial_k \phi_l \quad (\text{space & body frame locked})$$

$$\lambda_{ijke} = \lambda_{keli} = \lambda_{jike}$$

So the EOMs:

(neglect noise)

(momentum cons.)  $\partial_t g_i - \eta_{ijkl} \partial_j \partial_k v_l - \lambda_{ijkl} \partial_j \partial_k \phi_l = 0$

(Josephson rel.)  $\partial_t \phi_i - v_i = 0$   
 $\downarrow = K_{ij} g_j$

Combine: viscoelastic solid

$$\partial_t^2 g_{ij}^{-1} \phi_j = \underbrace{\lambda_{ijkl} \partial_j \partial_k \phi_l}_{\text{elastic}} + \underbrace{\eta_{ijkl} \partial_t \partial_j \partial_k \phi_l}_{\text{viscous}}$$

In an isotropic solid:

$$\eta_{ijkl} = \eta (\delta_{ik} \delta_{jl} + \delta_{il} \delta_{jk} - \frac{2}{d} \delta_{ij} \delta_{kl}) + f \delta_{ij} \delta_{kl}$$
$$\lambda_{ijkl} = \mu \left( \begin{array}{l} \text{shear} \\ \text{bulk} \end{array} \right) + K \delta_{ij} \delta_{kl}$$

$$g_{ij}^{-1} = \rho \delta_{ij} \quad \text{mass density}$$

Quasinormal modes:  $\phi \sim e^{ikx - i\omega t}$

longitudinal  $\vec{\phi} \parallel \vec{k}$ : (P wave) (sound)

$$\rho \omega^2 \phi_x = \left( \frac{2d-2}{d} \mu + K \right) k^2 \phi_x - i \omega k^2 \left( \frac{2d-2}{d} \eta + f \right) \phi_x$$

transverse:  $\phi \perp k$ : (S wave) (sound)

$$\rho \omega^2 \phi_\perp = \mu k^2 \phi_\perp - i \omega k^2 \eta \phi_\perp$$

e.g. S wave:  $\omega \approx \pm k \sqrt{\underbrace{\frac{\mu}{\rho}}_{v_s} - i \frac{\eta}{\rho} k^2} + \dots$

Unlike ordinary fluid... sound in transverse direction.

Note:  $v_p = \sqrt{\frac{4/3 \mu + K}{\rho}}$  ( $d=3$ )

$$\frac{v_p}{v_s} \geq \sqrt{\frac{4}{3}} \quad \text{since } \mu, K \geq 0.$$

e.g. earthquake physics: P waves hit first  
S waves second

Clear from EFT: Solids have viscosity.

$$\frac{\eta}{\rho} \sim 1 \frac{m^2}{s} \quad \leftrightarrow \quad \frac{\eta}{\rho} \sim 10^{-6} \frac{m^2}{s}$$

kinematic  
viscosity

vs  
water