

PHYS 7810  
Hydrodynamics  
Spring 2026

Lecture 3  
Time-reversal symmetry

January 15

Stochastic differential equation:  $\dot{x}_i = a_i(x) + b_{i\alpha}(x)\xi_\alpha(t)$   
with  $\langle \xi_\alpha(t) \rangle = 0$ ,  $\langle \xi_\alpha(t) \xi_\beta(s) \rangle = \delta_{\alpha\beta} S(t-s)$

↳ Fokker-Planck equation:  $\partial_t P(\vec{x}, t) = -\partial_i(a_i P) + \frac{1}{2} \partial_i \partial_j (b_{i\alpha} b_{j\alpha} P)$

In lecture 2 we saw that sometimes  $P(x, t)$  relaxes to a steady-state distribution at late times:

$\lim_{t \rightarrow \infty} P(\vec{x}, t) = P_{ss}(\vec{x}) \sim e^{-\Phi(\vec{x})}$  [neglect normalization].

Let's now think about things from reverse perspective. If we knew the form of  $e^{-\Phi}$ , what could we say about the FPE? In fact it will be instructive to re-derive FPE from a more phenomenological, "effective theory" perspective:

If  $\partial_t P = -\hat{W} P$ , what can  $\hat{W}$  be?  
↑  
formal differential operator

$$\textcircled{1} \quad \int dx_1 \cdots dx_n P = 1 \quad \text{at all times: } \int dx_1 \cdots dx_n \partial_t P = 0 ?$$

Since  $P(\vec{x}, t) \rightarrow 0$  as  $|\vec{x}| \rightarrow \infty$ , would hold if

$$\hat{W}P = \partial_i (\hat{A}_i P) \quad \text{since} \quad \int d^n x (-\partial_i (\hat{A}_i P)) = 0$$

$\nwarrow$  new differential op.  $\swarrow$  by divergence thm.

$$\textcircled{2} \quad \text{stationarity: } \hat{W}(e^{-\Phi}) = 0. \quad \text{holds if}$$

$$\hat{W}P = \hat{B}_j (\partial_j P + P \partial_j \Phi) = \hat{B}_j (\partial_j + \mu_j) P$$

$\hookrightarrow$  define  $\mu_j = \partial_j \Phi$

$$\text{since } (\partial_j + \mu_j) e^{-\Phi} = -\mu_j e^{-\Phi} + \mu_j e^{-\Phi} = 0.$$

Now let's combine these arguments:

$$\hat{W}P = -\partial_i \hat{Q}_{ij} (\partial_j + \mu_j) P$$

$\nwarrow$  general differential operator

One can show that if  $x$  lives on a simply connected space, ALL  $\hat{W}$  must take this form!

"effective theory"  $\Rightarrow$  expand  $\hat{Q}$  in derivatives  $\partial_k$ ?

leading order:  $\hat{Q}_{ij} = Q_{ij}(x) \Rightarrow$  Gaussian white noise!

In this class we will focus on this Gaussian noise limit...

This new perspective can bear further fruit if we make an analogy to QM. First, a mathematical analogy:

Green's function  $G(x, t; y)$  solves FPE w/  $G(x, 0; y) = \underbrace{S(x-y)}_{= \langle x|y \rangle}$ .

$\downarrow$

probability density  $y \rightarrow x$  in time  $t$

So  $G(x, t; y) = \langle x | e^{-\hat{W}t} | y \rangle$ . Indeed if  $P(x, t) = \langle x | P(t) \rangle$ , FPE is  $\frac{d}{dt} |P(t)\rangle = -\hat{W} |P(t)\rangle$ .

In QM, we can do more:

$$\langle x | e^{-iHt} | y \rangle = \langle y | e^{-iHt} | x \rangle^*$$

i.e. amplitude of  $y \rightarrow x$  matches  $x \rightarrow y$  (up to phase)

because  $H = H^\dagger$ .

For FPE:  $\langle x | e^{-\hat{W}t} | y \rangle = \langle y | e^{-\hat{W}^\dagger t} | x \rangle$  (linear algebra on real vector space...)

but  $\hat{W}^\dagger$  is NOT generator of another FPE!

How can we preserve structure of  $\hat{W}$  under "transpose"?

Recall:  $\hat{W} = \sum_i Q_{ij} (\partial_j + \mu_j) = \sum_i Q_{ij} e^{-\Phi} \partial_j e^\Phi$

$$\text{since } e^{-\Phi} \partial_j (e^\Phi f) = e^{-\Phi} \cdot e^\Phi (\partial_j f + \mu_j f) = (\partial_j + \mu_j) f$$

and since  $(\partial_i)^\dagger = -\partial_i$ : if  $Q$  doesn't have any  $\partial$ ...

$$\hat{W}^\dagger = e^\Phi (-\partial_j) e^{-\Phi} Q_{ij} (-\partial_i) = e^\Phi \partial_i Q_{ij} e^{-\Phi} \partial_j$$

$$\hookrightarrow \text{so } e^{-\Phi} \hat{W}^\dagger e^\Phi = \sum_i Q_{ji} e^{-\Phi} \partial_j e^\Phi = \sum_i Q_{ji} (\partial_j + \mu_j) = \hat{W}_{\text{rev}}$$

takes FPE form but  $Q$  has been transposed! (time-reversed  $\hat{W}$ )

Conclusion:  $\underbrace{\langle x | e^{-\hat{W}t} | y \rangle}_{\text{probability to transition from } y \rightarrow x \text{ in time } t} = \langle y | e^{-\hat{W}^\dagger t} | x \rangle$

$$= \langle y | e^\Phi e^{-\hat{W}_{\text{rev}} t} e^{-\Phi} | x \rangle$$

$$= e^{\Phi(y) - \Phi(x)} \underbrace{\langle y | e^{-\hat{W}_{\text{rev}} t} | x \rangle}_{\text{prob. } x \rightarrow y \text{ under reversed process}}$$

prob.  $x \rightarrow y$  under reversed process

Time-reversal symmetry:  $\hat{W} = \hat{W}_{\text{rev.}}$

$\downarrow$   
Detailed balance:  $\langle x | e^{-\hat{W}t} | y \rangle e^{-\Phi(y)} = \langle y | e^{-\hat{W}t} | x \rangle e^{-\Phi(x)}$

Now let's see that time-reversal was behind FDT:

$\hat{W} = -\partial_i Q_{ij} (\partial_j + \mu_j)$ , T-symmetric:  $Q_{ij} = Q_{ji}$

$$\hookrightarrow \partial_t P = -\partial_i \left[ (Q_{ij} \mu_j + \partial_j Q_{ij}) P \right] + \partial_i \partial_j [Q_{ij} P]$$

fluctuation-dissipation:  $Q_{ij} \mu_j$  dissipative force related to noise

let's see how this reconciles our confusion about time-reversal symmetry vs. arrow of time in dissipative systems:

Example 1:  $\dot{x} = -\mu x + \sigma \xi(t)$

lec 2  $\hookrightarrow e^{-\Phi} = e^{-\frac{\mu}{\sigma^2} x^2} \rightarrow$  Define  $\xi = \sigma \xi / \sqrt{\mu}$



DB:  $P(x_0 \rightarrow 0) e^{-(x_0/\xi)^2} = P(0 \rightarrow x_0)$

arrow of time! very unlikely to go to atypical configuration

Sometimes it's helpful to include other transformations as part of TRS:

Example 2: Brownian motion.

$$\dot{x} = P/m \quad \& \quad \dot{p} = \alpha \xi(t) \quad (\text{see also HW 1})$$

$\alpha = 0$ :  $T \cdot x = x$  &  $T \cdot p = -p$ . (momenta are odd under T)

Fokker-Planck  $\rightarrow$  Liouville equation in dissipationless limit:

$$\partial_t P + \partial_x \left( \frac{P}{m} \right) + \cancel{\partial_p (D \cdot P)} = 0, \text{ i.e. } \hat{W} = \partial_x \left( \frac{P}{m} \right)$$

under  $T$ :  $\hat{W}_{\text{rev}} = (-P/m)(-\partial_x) = \partial_x \left( \frac{P}{m} \right) = \hat{W}$

Note: steady state has translation symmetry so no  $\mu_x$  needed.

More generally could take "generalized" time-reversal:

$$\hat{W}_{\text{rev}} = e^{-\Phi} \sigma \hat{W}^T \sigma T e^{\Phi} \quad \text{where } T^2 = 1, \sigma \cdot \Phi = \Phi$$

In our example:

$$\sigma \begin{pmatrix} x \\ p \\ \partial_x \\ \partial_p \end{pmatrix} \sigma T = \begin{pmatrix} x \\ -p \\ \partial_x \\ -\partial_p \end{pmatrix}$$

"Generalized time-reversal symmetry":  $\hat{W}_{\text{rev}} = \hat{W}$ .

Often in physics we care about conserved quantities.

Noether's Thm: symmetry  $\Leftrightarrow$  conservation law in Hamiltonian mech.  
What to make of this in stochastic systems? A subtle thing  
is that there are actually 2 kinds of "symmetries..."

strong symmetry:  $F(x_1, \dots, x_n)$  conserved on every trajectory  
weak on average

Constraints on  $\hat{W}$ ?

Strong:  $[\hat{W}, F(x_1, \dots, x_n)] = 0$  (Analogy to QM!)

$$\downarrow \\ e^{-\lambda F} \hat{W} e^{\lambda F} = \hat{W} \text{ for any } \lambda$$

$$\downarrow \\ \hat{W}(x_i, \partial_i) = \hat{W}(x_i, \partial_i + \partial_i F)$$

Example 3: total momentum conservation

$$\dot{p}_1 = -\alpha(p_1 - p_2) + \beta \zeta(t) \quad \dot{p}_2 = -\alpha(p_2 - p_1) - \beta \zeta(t)$$

$\hookrightarrow \dot{p}_1 + \dot{p}_2 = 0$  Define  $\bar{p} = p_1 + p_2$

Fokker-Planck equation:

$$\begin{aligned} \partial_t P &= -\partial_{p_1} \left[ -\alpha(p_1 - p_2) P \right] - \partial_{p_2} \left[ -\alpha(p_2 - p_1) P \right] + \frac{1}{2} (\beta \partial_{p_1} - \beta \partial_{p_2}) \begin{pmatrix} \beta \partial_{p_1} \\ -\beta \partial_{p_2} \end{pmatrix} P \\ &= -(\partial_{p_1} - \partial_{p_2}) \left[ \alpha(p_1 - p_2) P \right] + \frac{\beta^2}{2} (\partial_{p_1} - \partial_{p_2})^2 P \end{aligned}$$

Shift:  $\partial_{p_1} \rightarrow \partial_{p_1} + \frac{\partial \bar{p}}{\partial p_1} = \partial_{p_1} + 1$ ,  $\partial_{p_2} \rightarrow \partial_{p_2} + \frac{\partial \bar{p}}{\partial p_2} = \partial_{p_2} + 1$

$$\partial_{p_1} - \partial_{p_2} \rightarrow \partial_{p_1} - \partial_{p_2} \text{ is invariant!}$$

weak:  $\frac{d}{dt} \int d^3x F(\vec{x}) P(\vec{x}, t) = 0$

$\downarrow$

$$\langle F | \frac{d}{dt} | P \rangle = -\langle F | \hat{W} | P \rangle = 0$$

$\downarrow$

$$\langle F | \hat{W} | P \rangle = 0.$$

Modify:  $\dot{p}_1 = -\alpha(p_1 - p_2) + \beta \zeta_I + \gamma \zeta_{II}$

$$\dot{p}_2 = -\alpha(p_2 - p_1) - \beta \zeta_I + \gamma \zeta_{II}$$

$\hookrightarrow \frac{d}{dt} \bar{p} = 2\gamma \zeta_{II}$

so  $\frac{d}{dt} \langle \bar{p} \rangle = 0$  but  $\bar{p}$  fluctuates on typical trajectories